in the Claims:

This listing replaces all previous versions and listings of the claims in this application.

1. (Currently amended) A method for determining an address of an actuator controlled by on a system bus, comprising:

identifying at least one end-stop for an actuator in a system having at least one actuator; and

determining an address for the actuator using based on the positioning of at least one end-stop of the actuator.

- 2. (Currently amended) The method of Claim 1, further comprising installing the actuator recording the address and downloading a control program for the actuator.
- 3. (Original) The method of Claim 1, wherein an actuator is identified using a single end-stop.
- 4. (Original) The method of Claim 1, wherein an actuator is identified using a position of a first end-stop relative to a second end-stop.
- 5. (Original) The method of Claim 1, wherein an actuator is identified using a position of an end stop and a reference.
- 6. (Currently amended) The method of Claim 1, wherein the a configuration of the at least one end stop is selected from the group consisting of linear and rotary.
- 7. (Original) The method of Claim 1, wherein at least one end-stop for the actuators is identified using an encoder.

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- 8. (Original) The method of Claim 1, wherein at least one end-stop for the actuator is identified using time.
- 9. (Original) The method of Claim 1, wherein at least one end-stop for the actuator is identified using an electronic integration function.
- 10. (Original) The method of Claim 1, wherein at least one end-stop for the actuator is identified using the step count of a stepper motor.
- 11. (Currently amended) The method of Claim 1, wherein at least one end-stop for the actuator is identified using phase angular information.
- 12. (Original) The method of Claim 1, wherein the actuators are identical except for their end stops.
 - 13. (Currently amended) A positioning apparatus, comprising: at least one actuator;
 - a control bus, operably connected to the at least one actuator; and
- a controller, operably connected to the control bus, wherein each actuator has at least one unique end-stop, and the address of each actuator $\frac{1}{2}$ determined by identifying said end-stop.
- 14. (Original) The apparatus of Claim 13, wherein the actuators are identical except for their respective end-stops.
- 15. (Original) The apparatus of Claim 13, wherein the control bus is connected to the actuators through a harness.

- 16. (Currently amended) The apparatus of Claim 15, wherein the harness has a number of wires selected from the group consisting of zero, one, two and three.
- 17. (Currently amended) The apparatus of Claim 13, further comprising a motor vehicle , wherein in which the apparatus is installed in the motor vehicle and in which the actuator acts to control a heating or cooling system of the motor vehicle.
 - 18. (Withdrawn) A method for heating and cooling a motor vehicle, comprising: providing a heating and cooling apparatus in the motor vehicle; installing at least one actuator in the apparatus;

determining a location of each actuator, each actuator having at least one endstop different from the end stops of the other actuators; and operating the apparatus.

- 19. (Withdrawn) The method of Claim 18, wherein determining is accomplished by exercising at least one actuator and identifying at least one end stop.
- 20. (Withdrawn) The method of Claim 18, wherein the actuators are identical except for the end-stops.